

# Improved PV Performance Modelling by Combining the PV\_LIB Toolbox with the Loss Factors Model (LFM)

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**Abstract** — PV project investments need comprehensive plant monitoring data in order to validate performance and to fulfil expectations. Algorithms from PV-LIB and Loss Factors Model are being combined to quantify their prediction improvements at Gantner Instruments’ Outdoor Test facility at Tempe AZ on multiple Tier 1 technologies. The validation of measured vs. predicted long term performance will be demonstrated to quantify the potential of IV scan monitoring. This will give recommendations on what parameters and methods should be used by investors, test labs, and module producers.

**Index Terms** — Energy, Meteorology, Modeling, Photovoltaic systems, Power, Simulation.

## I. INTRODUCTION

PV project investments require continuous, accurate and traceable plant monitoring data in order to determine the actual vs. design performance and to fulfil owner/investor expectations.

Algorithms from the “PV Performance Modeling Collaborative” (PVP MC) and “Loss Factors Model” (LFM) are being combined to test out their prediction improvements at Gantner Instruments’ (GI) Outdoor Test facility at Tempe AZ on multiple Tier 1 technologies including c-Si, CdTe and CIGS.

The PV\_LIB Toolbox was originally developed at Sandia National Laboratories and has been expanded by contributions from members of the PVP MC [1]. A standard library of PV algorithms includes solar position, irradiance translation, module temperature, and array and inverter performance. PV\_LIB is available in MatLab and Python versions [2] [3].

The LFM has been developed and is being used by SRCL and Gantner Instruments to produce optimum PV performance simulation accuracy with determination of performance coefficients, quantification of any instability and fault finding diagnosis [4] [5].

The validation and comparisons of the measured vs. predicted (long term) performance will be demonstrated in this paper to quantify the potential benefits of continuous IV scan monitoring. We will provide recommendations on what parameters and methods should be used by investors, test labs, and module producers. Validated functions are available in the [gantner-webportal.com](http://gantner-webportal.com) for advanced utility scale analysis and prediction. Providing more accurate performance analysis,

indication of abnormal loss or trends leads to more effective O&M and risk reduction for owners.

## II. OUTDOOR MEASUREMENTS

Gantner Instruments’ Outdoor Test facility (OTF) in Tempe, AZ (figure 1) measures IV curves every minute for 24 fixed modules and 6 on a 2D tracker [6]. It has been running since July 2010 with a 98.9% uptime. Table I lists some of the GI OTF meteorological measurements.

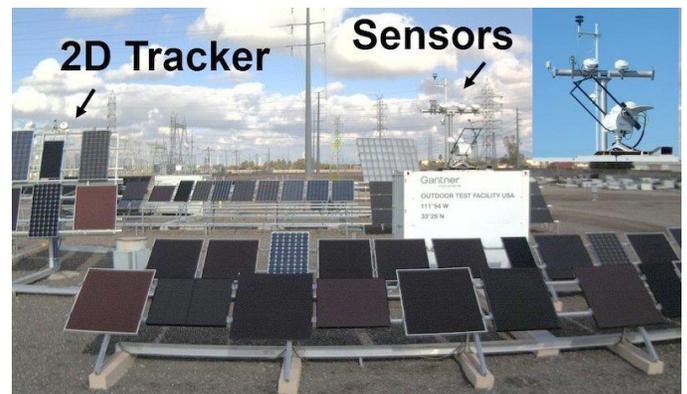


Fig. 1. Gantner Instruments OTF in Tempe, Arizona.

TABLE I.  
GI OTF MEASUREMENTS

Name	Description	Units
G <sub>H</sub>	Global Horizontal Irradiance	kW/m <sup>2</sup>
D <sub>H</sub>	Diffuse Horizontal Irradiance	kW/m <sup>2</sup>
B <sub>N</sub>	Beam Normal Irradiance	kW/m <sup>2</sup>
G <sub>I</sub>	Global Inclined Irradiance (Pyranometers and c-Si ref cells)	kW/m <sup>2</sup>
T <sub>AMB</sub>	Ambient Temperature	C
T <sub>MOD</sub>	Back of Module Temperatures	C
WS	Wind Speed	ms <sup>-1</sup>
WD	Wind Direction	°
RH	Relative Humidity	%
G(λ)	Spectral Irradiance G(350– 1050nm)	W/m <sup>2</sup> /nm

### III. VALIDATING PV\_LIB AND LFM ALGORITHMS

Using synchronized, 1 minute measured data from a year at the Tempe Site (which is defined by its latitude and longitude; array tilt and azimuth) calculations were made with the PV\_LIB routines and checked with existing site calculations (e.g. solar position), actual meteorological measurements (irradiance, temperature, spectrum etc.) and measured PV performance as below (A to F).

#### A. "GI Calculated" vs. PV\_LIB Solar Position

The PV\_LIB solar elevation and azimuth (calculated using the *pvl\_spa* function) were compared with the predictions from the GI site, which used a less sophisticated algorithm (SUNAE) to calculate sun position. Differences are shown in figure 2. Both azimuth and elevation are mostly within  $\pm 2^\circ$ . These differences are typical, since the *pvl\_spa* model is based on NREL's Sun Position Algorithm [7] which includes details not addressed by simpler models (e.g., refraction, nutation, etc.).

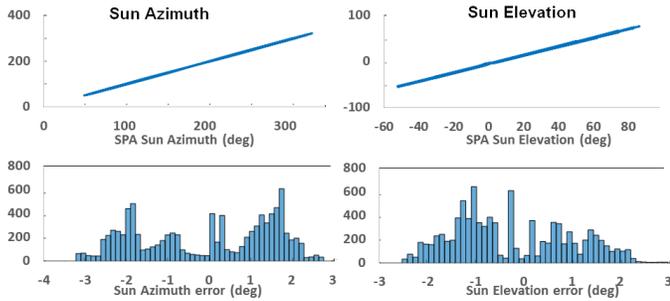


Fig. 2. Comparing PV\_LIB calculations of solar elevation and azimuth with the internal data from GI

#### B. Predicted Tilted Irradiance from Diffuse Sky Model

Figure 3 shows the correlation between six anisotropic or isotropic sky models calculated vs. measured GI.

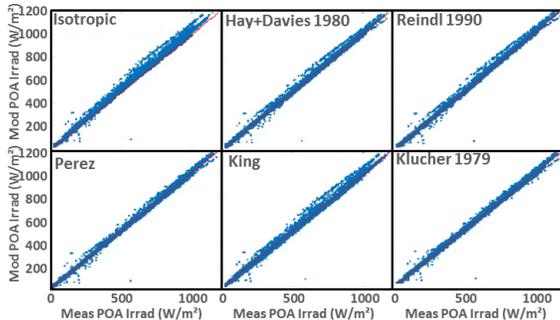


Fig. 3. Comparing calculated vs. measured tilted plane irradiance from six PV\_LIB anisotropic or isotropic diffuse sky models (*pvl\_isotropicsky*, *pvl\_haydavies\_1980*, *pvl\_reindl\_1990*, *pvl\_perez*, *pvl\_kingdiffuse*, and *pvl\_klucher\_1979*).

PV\_LIB contains several methods for estimating tilted global  $G_T$ , as a function of diffuse horizontal  $D_H$  and beam normal  $B_N$  (with angle of incidence).

#### C. Spectral Content vs. Solar Altitude and Azimuth

Blue Fraction is defined as "blue light"/"c-Si absorbable light" (1) and is an alternative to the average photon energy (APE) which depends on the lower and upper limits of measured wavelength.

$$\text{Blue Fraction} = \frac{\sum G_{350-650 \text{ nm}}}{\sum G_{350-1050 \text{ nm}}} \quad (1)$$

For AM1.5 the Blue Fraction  $\sim 0.52$ , a higher number comes from a bluer spectrum, a lower value means redder than AM1.5.

At most sites the solar spectrum is not measured but if needed is inferred from solar elevation angles. This may work well under clear sky conditions but not so well under cloudy skies where the clouds absorb more red light than blue. GI use the Blue Fraction as a "rule of thumb" to roughly quantify spectral irradiance.

Figure 4 gives the measured Blue Fraction (y axis) vs. Air Mass (derived just from the solar height - x axis) for different clearness indices (kTh) from 0.2 (mostly obscured) to 1.0 (clear) at the GI Tempe site. Clear skies usually have a kTh $\sim 0.8$  (meaning 80% of the extraterrestrial horizontal irradiance reaches the ground, the other 20% is absorbed or reflected by the atmosphere). This is shown in pale green with linear fits from AM1 to AM6. The value at AM1.5 is around 52% and it falls around 2% for each "integer AM" increase. Other clearness indexes follow a similar trend with the overall shift being towards blue rich when the clearness falls.

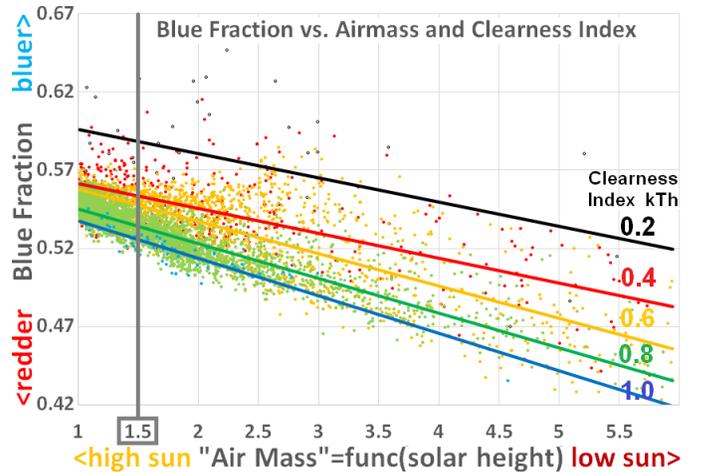


Fig. 4. Measured Blue Fraction vs. Air Mass (Solar height) for different clearness indices at the GI site at Tempe.

Figure 5 plots the average measured blue fraction vs. solar altitude and azimuth for 1 minute data at the GI Tempe facility (which has predominantly clear skies).

A Blue Fraction of 0.52~AM1.5 is shown in yellow with other colours indicating bluer or redder spectra. In general the higher the solar altitude then the bluer the spectrum and vice versa – also a little bluer (clearer) in the morning than the afternoon. There are two spots of “very blue rich light >0.59” at low solar altitude and azimuths of <80 ENE ❶ and >280 WNW ❷ when the sun is behind the module so there’s no direct light, only diffuse and hence a bluer than expected spectrum.

There is also a localized spot of blue rich light at 100° azimuth and 10° solar altitude ❸ which we will identify in the next section D.

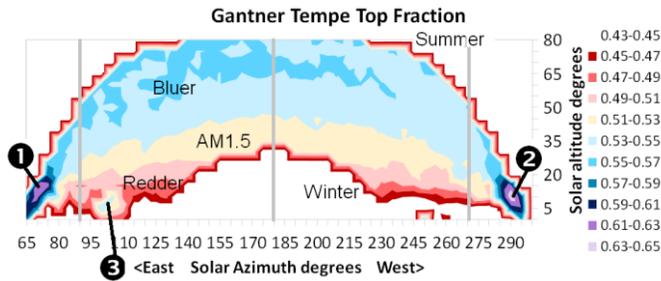


Fig. 5. Average measured Blue Fraction vs. solar altitude and solar azimuth for GI’s Tempe facility

#### D. Isc vs Angle of Incidence and Shading

Figure 6 plots the normalized Isc (2) for a standard c-Si screen print module vs. solar altitude and azimuth at GI Tempe.

$$nI_{SC} = \frac{I_{SC,MEASURED}}{I_{SC,STC} \cdot G_{cSi,REFCELL}} \quad (2)$$

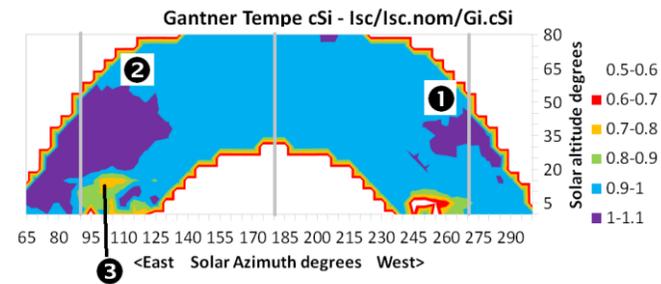


Fig. 6. Average normalized Isc vs. solar altitude and solar azimuth for a typical c-Si module at GI’s Tempe facility

$nI_{SC}$  is smooth over most of the solar positions, becoming a little higher for large azimuths away from south <90 ENE ❷ and >270 WNW ❶ (presumably the ARC on the c-Si module gives better off axis reflectivity than the reference cell). However at point ❸ (as in figure 3) the current drops 20-30% suggesting it was due to shading. This would filter out some of

the red direct light from the low sun making the resultant spectrum go bluer as seen in figure 3.

#### E. Module Temperature Rise Above Ambient vs. Wind Speed (and Irradiance)

Module and cell temperatures rise above ambient depending on plane of array irradiance, wind speed, the manufacturing technology (e.g. glass-glass, glass-polymer etc.) and also the mounting method (e.g. freely ventilated back, insulated back, bipv etc.) [8]. The relevant PV\_LIB function is

$$pv1\_sapmcelltemp(E=Irradiance, Wspd, Tamb, modelt)$$

There are three empirical coefficients dependent on the technology and mounting method. Recommended values can be found on the PVPVC website.

Figure 7 plots the modelled vs. measured average temperature rise above ambient vs. wind speed (x axis) and irradiance (plots) for a free back CdTe module at GI’s Tempe site using the default PV\_LIB coefficients. A good overall agreement can be seen with discrepancies generally  $\pm 2C$ . (The empirical coefficients could be further optimized to give a better fit for yield prediction.)

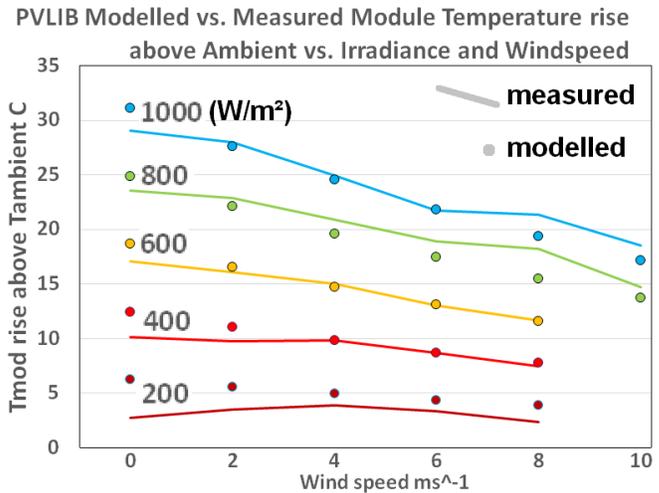


Fig. 7. PV\_LIB modelled vs. average measured module temperature rise above  $T_{AMB}$  for a CdTe module at GI Tempe against wind speed (x axis) and irradiance (lines).

#### F. Sensor Angle of Incidence

Pyranometers tend to have a slightly better angular acceptance response than c-Si reference cells as their domes reflect less light away than a flat plate panel even with antireflective coating. Figure 8 shows the results of comparing the irradiance reported by a plane of array pyranometer versus a plane of array crystalline reference cell vs. horizontal beam fraction and angle of incidence for GI’s Tempe site. This can be used to perform angle-of-incidence (AOI) corrections for flat plate panels with only pyranometer sensors – when c-Si

reference cells are used then the angular correction needed is small. Beam fractions are usually between 0.2 (mostly diffuse) and 0.8 (mostly direct), at the GI Tempe site the angle of incidence only gets below  $10^\circ$  for a short time (spring/autumn equinox at solar noon) also data above  $80^\circ$  AOI has a lot of scatter so the graph does not include some extreme values for clarity. Nevertheless the  $G_{c-Si}/G_{PYR}$  approaches 100% for angle of incidence  $<10^\circ$  at any beam fraction (as expected from calibrated sensors but note there's no spectral correction) and falls off as the angle of incidence increases, slightly faster under direct than diffuse conditions. As a rule of thumb the graph suggests a value of about 85% at an AOI of  $65^\circ$  and  $BF=0.5$  meaning the c-Si sensor would predict a 15% better low light coefficient than the pyranometer would suggest under these conditions

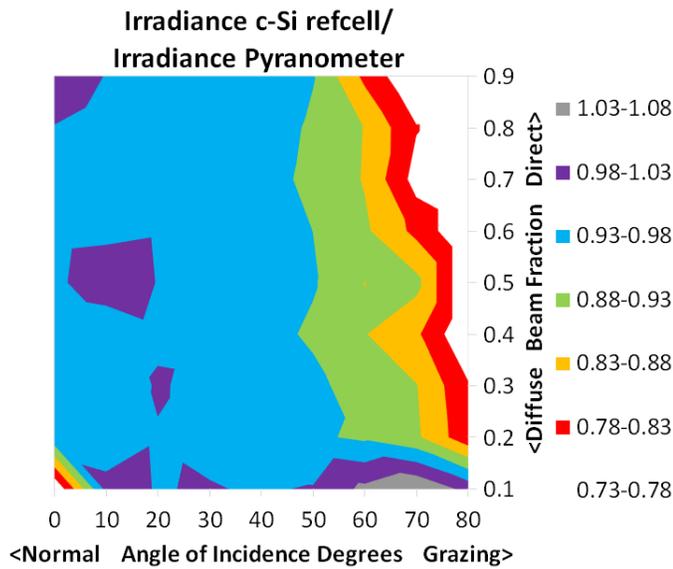


Fig. 8. Average irradiance measured by the POA c-Si reference cell divided by that from a POA pyranometer measured at GI Tempe. No spectral corrections are done.

#### IV. THE LOSS FACTORS MODEL (LFM)

The LFM fits IV curves very well under normal weather conditions [4].

Previously LFM values have been derived by normalizing measurements with a c-Si reference sensor. Fits have been done to “good conditions” i.e. reasonable high irradiance, near noon (so low angle of incidence), unshaded and non-snow covered conditions. Extreme conditions for parameter fitting have been removed by filtering on limits (such as ‘AOI $<60$  degrees’ or ‘sun height  $>15^\circ$ ’) to get rid of the “scattered” points that may be hard to fit but filtering gets rid of some good points too. For example if there is a building shading  $15$  degrees high to the east but a low horizon to the west, filtering ‘sun height $>15^\circ$ ’ removes some otherwise good low solar height measurements in the west.

The PV\_LIB functions already contain PV models (including the 1-diode and SAPM) but in this work the LFM is included to improve the modelling accuracy [5]. An outcome of this work will be to add the LFM to the PV\_LIB Toolbox, allowing greater access.

The LFM is illustrated in figure 9 [4]. It analyses IV curves at different outdoor conditions (irradiance, module temperature, spectrum, angle of incidence etc.) to give six normalized orthogonal parameters (as in Table II) that characterize a module’s performance and can identify the cause and any rate of change of limiting parameters. The product of these 6 parameters gives the normalized efficiency (also known as the DC performance ratio  $PR_{DC}$ ).

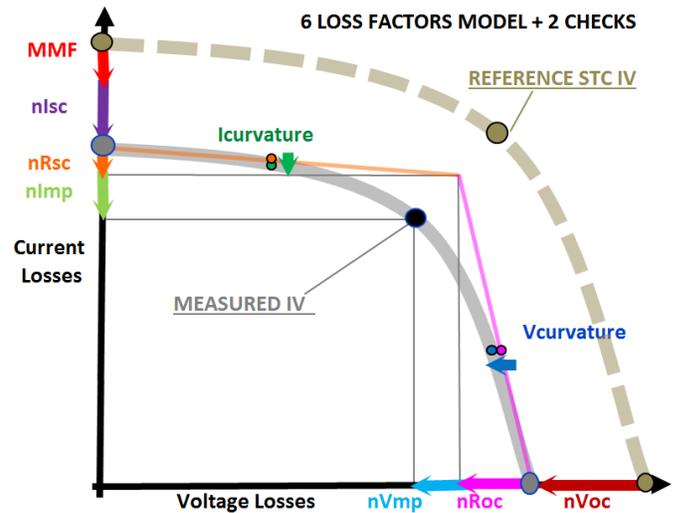


Fig. 9. Simplified SRCL/Gantner Instruments Loss Factors Model

TABLE II.  
NORMALIZED LFM PARAMETERS

LFM	Performance determining factors include
$n_{LSC}$	Spectral mismatch, dirt, snow, beam reflectivity vs. AOI
$n_{RSC}$	$R_{SHUNT}(G_i)$
$n_{IMP}$	$IMP(G_i)$ corrected for $R_{SC}$
$n_{VMP}$	$V_{MP}(G_i)$ corrected for $R_{OC}$
$n_{ROC}$	$G_i^2 * R_{SERIES}(G_i)$
$n_{VOC}$	$V_{OC}(G_i) \sim \ln(G_i/I_0)$ , $T_{MODULE}$
$PR_{DC}$	$= (n_{LSC} * n_{RSC} * n_{IMP}) * (n_{VMP} * n_{ROC} * n_{VOC})$

#### A. PV Performance vs. Irradiance and Temperature

PV module performance is measured over a period of time at differing meteorological conditions such as irradiance, ambient temperature, angle of incidence and spectrum. The 6 LFM parameters are then characterized by fitting as functions of irradiance and temperature. On line checks of performance can be undertaken by comparing measured with data predicted from the earlier test method.

## V. IMPROVEMENTS TO LFM FITS USING EMPIRICAL MODELS OF TOP FRACTION AND AOI

Figure 10 shows predicted vs. measured performance of a CdTe module (top) and a c-Si module (bottom) at Tempe for ~750 random data points.

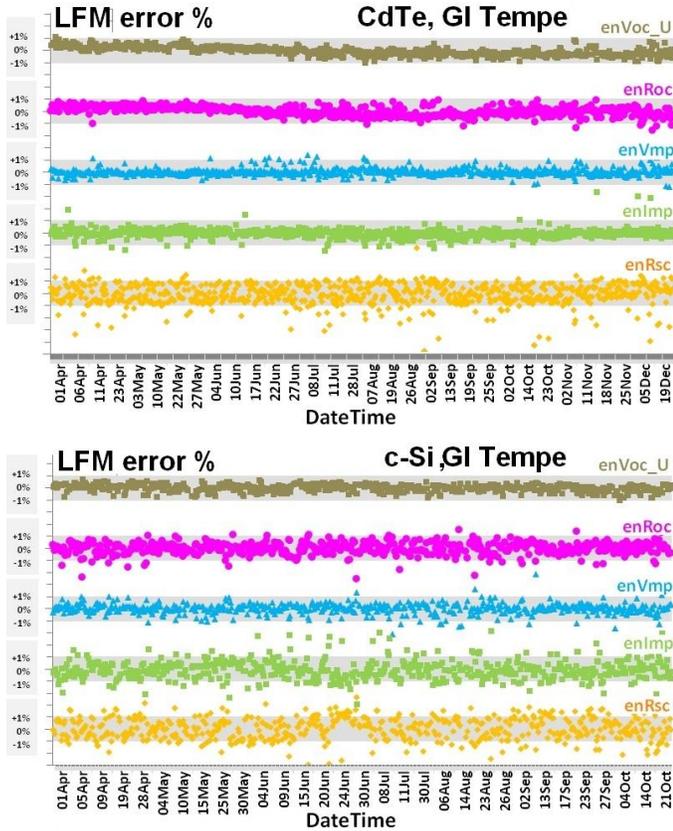


Fig. 10. Prediction accuracy for 5 LFM parameters measured (dark dots) vs. calculated (light grey lines  $\pm 1\%$ ) for a CdTe (top) and c-Si (bottom) for GI Tempe.

For well-behaved modules the five LFM parameters (except  $nI_{SC}$ ) can usually be fitted to  $< \pm 1\%$  accuracy shown as the grey horizontal lines (i.e. the coloured dots are usually within the grey lines for a good fit).

The fit for  $nI_{SC}$  is also affected by soiling, snow, angle of incidence reflectivity and spectral response.

It is important to know the  $T_{MODULE}$  for the  $nV_{OC}$  coefficient. If this is not known then it can be calculated from the PV\_LIB `pv1_sapmcelltemp`

Using some of the previously described empirical fits for spectrum, angle of incidence and module temperature the following improvements are seen

### A. $nI_{SC}$ vs. Spectral Content vs. Solar Altitude and Azimuth

Figure 11 shows the  $nI_{SC}$  error for a CdTe module against a c-Si irradiance sensor both without (top) and with (bottom) corrections of the ISC predicted from the blue fraction. The

corrected  $nI_{SC}$  has lessened from  $\sim 10\%$  (max in summer) to now mostly within  $\pm 2\%$  (flat over the year) with only a small ripple around November and December when the sun is lowest and the correction needed is greatest and most uncertain

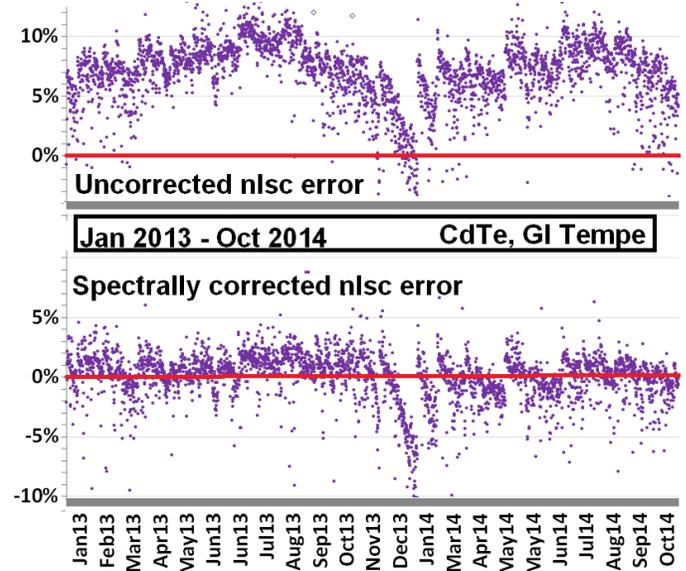


Fig. 11. Improvement to modelled  $nI_{SC}$  errors from empirical spectral correction (bottom) for a CdTe module at GI Tempe

### B. $nI_{SC}$ vs. Sensor Type Angle of Incidence

Figure 12 shows the modelled vs. measured  $nI_{SC}$  error for a c-Si module against a c-Si irradiance sensor and pyranometer

(a) vs. a c-Si reference cell. Most points are within  $< \pm 1\%$  but there is a degree of scatter

(b) vs. a pyranometer uncorrected for aoi. The best errors are  $< \pm 1\%$  (when the aoi is low so corrections aren't needed), when the aoi is high the errors can be worse than  $-15\%$  (see figure 8 – this loss is expected from an aoi of 75degrees)

(c) vs. a pyranometer empirically corrected for aoi. The average errors are now  $< \pm 2\%$  but this can probably be improved a little by parameter optimization.

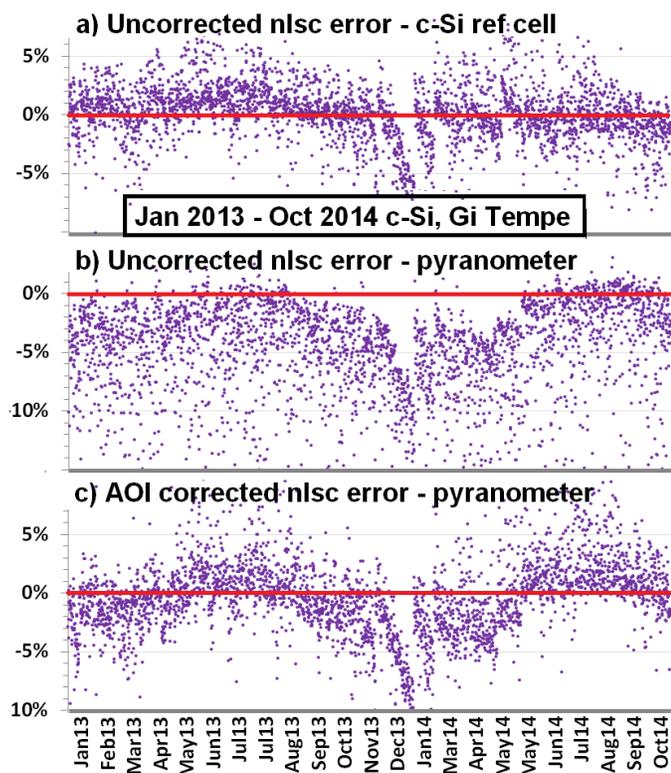


Fig. 12. Improvement to modelled nIsc errors from empirical angle of incidence correction for a c-Si reference cell and a pyranometer for a c-Si module at GI Tempe.

## VI. CONCLUSIONS

PV\_LIB is being integrated into Gantner Instruments measurement data and analysis methods [9]

LFM is compatible in line with PV\_LIB algorithms and will gain further understanding for modelling

Efficient data filters allow more reliable data analysis and interpretation

Standardization of algorithms, reduction of site specific impacts allows reliable plant benchmarking within the portfolio

Empirical modelling with PV\_LIB functions enhances LFM fits leading to reduced errors even without spectral information, reference cell or module temperature measurements.

Gantner Instruments will introduce LFM and PV\_LIB to its real time platform ([gantner-webportal.com](http://gantner-webportal.com)) which enables more accurate utility scale performance verification, analysis and prediction.

This provides more accurate performance analysis, indication of abnormal loss or trends leading to more effective O&M and risk reduction for owners on a real time basis.

Performance guarantees – target versus actual performance – can be validated more reliable as the difference can be linked to the integrated loss stages where optimization potential (in terms of kWh or \$) can be identified as well.

Sandia National Laboratories plans to incorporate the LFM model into the next release of the PV\_LIB Toolbox.

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